

Monroe D. Kennedy III, Ph.D.

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Assistive Robotics and Manipulation (ARM) Laboratory

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Curriculum vitae last updated: January 15, 2025

Education

Ph.D. 2019 Mechanical Engineering Applied Mechanics, University of Pennsylvania

Dissertation: Modeling and Control for Robotic Assistants: Single and Multi-robot Manipulation

M.S. 2016 Robotics, University of Pennsylvania

B.S. 2012 Mechanical Engineering, University of Maryland Baltimore County

A.S. 2006 Cuyahoga Community College

Positions Held

- **2019-present** Assistant Professor, Mechanical Engineering Department, Stanford University
- **2021-present** Courtesy appointment, Computer Science Department, Stanford University
- **2019** Technical Staff in Group 76, MIT Lincoln Laboratory

Research Interests

My research focuses on developing principles and tools needed to realize collaborative robotics (human-robot collaboration), robotic autonomy and robotic manipulation. Topics that are of particular interest to me include: (1) Robotic Assistants: collaborative robots that work for or alongside human teammates and require modeling of complex tasks and (human) teammate behavior. (2) Connected Devices: passive robotic platforms that enhance an ability of the human user and leverage situational awareness to assist and predict the human users needs. (3) Intelligent Wearables: devices that either augment or enhance a humans ability and is worn on the individual, such devices require situational awareness, and prediction of users intent and actions in order to serve the human users needs. Solutions rely on combination of tools in dynamical systems analysis, control theory (classical, non-linear and robust control), state estimation and prediction, motion planning, vision for robotic autonomy and machine learning. Application areas include autonomous assistive technology, robotic assistants with the goal of deployment for service tasks that may be highly dynamic and require dexterity, situational awareness, as well as human-robot collaboration.

Awards and Certificates

- National Science Foundation Faculty Early Career Development (CAREER) Award - Foundational Robotics Research (FRR), CMMI. Award number [2142773](#).
- National Science Foundation Graduate Fellow [University of Pennsylvania]
- GEM Fellow [University of Pennsylvania]
- Outstanding Teaching Assistant Award in Mechanical Engineering [University of Pennsylvania]
- Center for Teaching and Learning (CTL) Teaching Certificate [University of Pennsylvania]
- Meyerhoff Scholar [University of Maryland, Baltimore County]
- Tau Beta Pi Honors Society [University of Maryland, Baltimore County]

Journal Articles

- [1] Shivani Guptasarma and Monroe D. Kennedy. Proact: An augmented reality testbed for intelligent prosthetic arms. *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, 33:354–365, 2025.
- [2] Won Kyung Do, Bianca Aumann, Camille Chungyoun, and Monroe Kennedy. Inter-finger small object manipulation with densetact optical tactile sensor. *IEEE Robotics and Automation Letters*, 9(1):515–522, 2024.

- [3] Eley Ng, Ziang Liu, and Monroe Kennedy. Diffusion co-policy for synergistic human-robot collaborative tasks. *IEEE Robotics and Automation Letters*, 9(1):215–222, 2024.
- [4] Jose A. Solano-Castellanos, Won Kyung Do, and Monroe D. Kennedy. Embedded Object Detection and Mapping in Soft Materials Using Optical Tactile Sensing. *SN Computer Science*, 5(4):372, 2024.
- [5] **Monroe Kennedy**, Karl Schmeckpeper, Dinesh Thakur, Jiang Chenfanfu, Vijay Kumar, and Kostas Daniilidis. Autonomous precision pouring from unknown containers. *IEEE Robotics and Automation Letters*, 4(3):2317–2324, 2019.
- [6] Caio Mucchiani, **Monroe Kennedy**, Mark Yim, and Jun Seo. Object picking through in-hand manipulation using passive end-effectors with zero mobility. *IEEE Robotics and Automation Letters*, 3(2):1096–1103, April 2018.
- [7] **Monroe Kennedy**, Dinesh Thakur, M Ani Hsieh, Subhrajit Bhattacharya, and Vijay Kumar. Optimal paths for polygonal robots in se (2). *Journal of Mechanisms and Robotics*, 10(2):021005, 2018.
- [8] Edward Steager, Mahmut Selman Sakar, Magee Ceridwen, **Monroe Kennedy**, Anthony Cowley, and Vijay Kumar. Automated biomanipulation of single cells using magnetic microrobots. *The International Journal of Robotics Research*, 32(3):346–359, 2013.

Refereed Conference Articles

- [1] Won Kyung Do, Ankush Kundan Dhawan, Mathilda Kitzmann, and Monroe Kennedy. Densetact-mini: An optical tactile sensor for grasping multi-scale objects from flat surfaces. In *2024 IEEE International Conference on Robotics and Automation (ICRA)*, pages 6928–6934, 2024 (Best Paper Nomination).
- [2] Aiden Swann, Matthew Strong, Won Kyung Do, Gadiel Sznaier Camps, Mac Schwager, and Monroe Kennedy. Touch-gs: Visual-tactile supervised 3d gaussian splatting. In *2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, pages 10511–10518, 2024.
- [3] Won Kyung Do, Bianca Jurewicz, and Monroe Kennedy. Densetact 2.0: Optical tactile sensor for shape and force reconstruction. In *2023 IEEE International Conference on Robotics and Automation (ICRA)*, pages 12549–12555, 2023.
- [4] Eley Ng, Ziang Liu, and Monroe Kennedy. It takes two: Learning to plan for human-robot cooperative carrying. In *2023 IEEE International Conference on Robotics and Automation (ICRA)*, pages 7526–7532, 2023.
- [5] Weizhuo Wang, Michael Raitor, Steve Collins, C. Karen Liu, and Monroe Kennedy. Trajectory and sway prediction towards fall prevention. In *2023 IEEE International Conference on Robotics and Automation (ICRA)*, pages 10483–10489, 2023.
- [6] Won Kyung Do and Monroe Kennedy. Densetact: Optical tactile sensor for dense shape reconstruction. In *2022 International Conference on Robotics and Automation (ICRA)*, pages 6188–6194, 2022.
- [7] Albert H. Li, Philipp Wu, and Monroe Kennedy. Replay overshooting: Learning stochastic latent dynamics with the extended kalman filter. In *2021 IEEE International Conference on Robotics and Automation (ICRA)*, pages 852–858, 2021.
- [8] Monroe Kennedy, Kendall Queen, Dinesh Thakur, Kostas Daniilidis, and Vijay Kumar. Precise dispensing of liquids using visual feedback. In *2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, pages 1260–1266, Sept 2017.
- [9] Mabel Zhang, Monroe Kennedy, M. Ani Hsieh, and Kostas Daniilidis. A triangle histogram for object classification by tactile sensing. In *2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, pages 4931–4938, Oct 2016.
- [10] **Monroe Kennedy III**, Luis Guerrero, and Vijay Kumar. Decentralized algorithm for force distribution with applications to cooperative transport. In *ASME 2015 International Design Engineering Technical Conferences and Computers and Information in Engineering Conference*, volume 5C: 39th Mechanisms and Robotics Conference of *International Design Engineering Technical Conferences and Computers and Information in Engineering Conference*. American Society of Mechanical Engineers, Aug 2015. V05CT08A013.

Editorials/Invited/Non-refereed/Short Conference Articles and Abstracts

- [1] Shivani Guptasarma, Brian B. Vuong, Allison M. Okamura, and Monroe Kennedy III. Facial haptic feedback for robotic prostheses. In Jose L. Pons, Jesus Tornero, and Metin Akay, editors, *Converging Clinical and Engineering Research on Neurorehabilitation V*, pages 311–315, Cham, 2024. Springer Nature Switzerland.
- [2] Monroe Kennedy. The role of collaborative robotics in assistive and rehabilitation applications. *Science Robotics*, 8(83):eadk6743, 2023.
- [3] Eley Ng, Ziang Liu, and Monroe Kennedy. Learning action and state sampling distributions from offline data for human-robot collaboration. In *Workshop on Learning from Diverse, Offline Data*, 2022.
- [4] Shivani Guptasarma and Monroe Kennedy III. Considerations for the Control Design of Augmentative Robots. In *IEEE International Conference on Intelligent Robots and Systems Workshop on Building and Evaluating Ethical Robotic Systems*, number 1, Prague, Czech Rep, 2021.
- [5] Ayanna Howard and Monroe Kennedy III. Robots are not immune to bias and injustice. *Science Robotics*, 5(48), Nov 2020.
- [6] Junwu Zhang and Monroe Kennedy. Recent development in human motion and gait prediction. *Workshop on Robot Retrospectives, Robot Science and Systems*, 2020.
- [7] Monroe David Kennedy III. *Modeling and Control for Robotic Assistants: Single and Multi-Robot Manipulation*. Phd, University of Pennsylvania, jan 2019.

Professional Service

International Program, Editorial, and Review Committees

- Accessibility & Inclusion Committee Co-Chair, IEEE International Conference on Robotics and Automation (ICRA) 2025
- NSF Grant Review Panelist 2024
- Reviewer for IEEE Transactions on Automation Science and Engineering 2024
- Reviewer for IEEE Transactions on Robotics 2024
- Reviewer for IEEE International Conference on Robotics and Automation (ICRA) 2020-2025
- Reviewer for IEEE Transactions on Instrumentation & Measurement 2023
- Associate Editor for IEEE International Conference on Robotics and Automation (ICRA) 2020,2022-2023
- Conference Session Chair (Contact Modeling, Grippers, and other End-Effectors), IEEE ICRA 2022
- Reviewer for IEEE Transactions on Neural Systems and Rehabilitation Engineering 2022
- Workshop Program Committee (Building and Evaluating Ethical Robotics Systems), IEEE International Conference on Intelligent Robots and Systems (IROS) 2021
- Conference Session Chair (Automation: Machine Learning II), IEEE ICRA 2021
- Reviewer for Transactions on Human-Robot Interaction 2021
- Guest Editor for Field Robotics: *Robotics Collaborative Technology Alliance (RCTA)– Developing Autonomous Robotic Team Members for Unstructured Environments* 2020-2021
- Reviewer for International Journal of Robotics Research 2019
- Reviewer for IEEE International Conference on Automation Science and Engineering (CASE) 2018
- Reviewer for ASME International Design Engineering Technical Conferences 2017-2018
- Reviewer for IEEE Robotics and Automation Letters (RA-L) 2017 - 2023 (every year)
- Reviewer for IEEE International Conference on Intelligent Robots and Systems (IROS) 2014-2016

Administrative and Organizational Committees

- [Black in Robotics](#) (non-profit) co-founder, board member, National co-Director, and Bay Area Chapter co-Director 2020-present

University Service

Graduate Admissions Committee, Department of Mechanical Engineering (2019-present)
Knight-Hennessy Scholar Annual Candidate Interviewer, Stanford University (2020-2023)
Diversity, Equity and Inclusion Committee, Department of Mechanical Engineering (2020-2022)
Co-lead of Robotics and Autonomous Systems Area, SystemX Stanford University, (2020-present)

Professional Affiliations

- Member, American Society of Mechanical Engineers
- Member, Institution of Electrical and Electronic Engineers

Press Coverage and Media Appearances

- [Why the Future Needs Robots with a Human Touch](#)
- [KUKA Innovation award Finalist 2018](#)
- [Exploration Earth 2050 “Bio-Mechanimals” \(S1E1\)](#)
- [Bloomberg Technology: “The End of Traffic: How the Smartest People in the World Are Fixing Your Commute”](#)
- [Xploration Nature Knows Best \(S1E12\)](#)

Advising

Doctoral and Pre-doctoral Students

Shalika Neelaveni, Ph.D. student, Stanford Mechanical Engineering, expected 2030.

Max Burns, Ph.D. student, Stanford Mechanical Engineering, expected 2030.

Jinho So, Ph.D. student, Stanford Mechanical Engineering, expected 2030.

Matthew Strong, Ph.D. student, Stanford Computer Science, expected 2029.

Aiden Swann, Ph.D. student, Stanford Mechanical Engineering, expected 2029. NSF Graduate Fellow

Aliyah Smith, Ph.D. student, Stanford Aeronautics & Astronautics, expected 2026. NSF Graduate Fellow.

Weizhuo (Ken) Wang, M.S. in Aeronautics & Astronautics, Stanford University, expected 2026.

Shivani Guptasarma, Ph.D. student, Stanford Mechanical Engineering, expected 2025. Knight-Hennessy Scholar, Wu Tsai Human Performance Fellow.

Won Kyung Do, Ph.D. student, Stanford Mechanical Engineering, expected 2025.

Eley Ng, Ph.D., Stanford Mechanical Engineering, **Graduated 2023**. NSF Graduate Fellow.

Masters Research Students

*=publication

Aditya Dutt, M.S. in Mechanical Engineering, Stanford, expected 2025

Alex Qiu, M.S. in Mechanical Engineering, Stanford, expected 2026

David Ihim, M.S. in Mechanical Engineering, Stanford, graduated 2025

Giuse Pham, M.S. in Mechanical Engineering, Stanford, expected 2026

Jiaqi Shao, M.S. in Mechanical Engineering, Stanford, expected 2026

Judith Brown, M.S. in Mechanical Engineering, Stanford, expected 2025

Omoruyi Atekha, M.S. in Mechanical Engineering, Stanford, expected 2025

Rohan Punamiya, M.S. in Mechanical Engineering, Stanford, expected 2026

Sam Morstein, M.S. in Mechanical Engineering, Stanford, expected 2025

Vakula Venkatesh, M.S. in Mechanical Engineering, Stanford, expected 2026

Yunxin Fan, M.S. in Mechanical Engineering, Stanford, expected 2025

Zhongchun Yu, M.S. in Mechanical Engineering, Stanford, expected 2025

Camille Chungyoun*, M.S. in Mechanical Engineering, Stanford, graduated 2024

Rafael Sonderegger, M.S. in Mechanical Engineering, ETH Zurich, Fall 2023

HongHao Zhen, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Heidi Kwong, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Karina Ting, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Tejas Deo, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Jose Castellanos*, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Saksham Consul, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Dev Savla, M.S. in Mechanical Engineering, Stanford University, graduated 2024

Bianca Jurewicz**, M.S. in Mechanical Engineering, Stanford University, graduated 2023

Ziang Liu*, M.S. in Computer Science, Stanford University, graduated 2023

Blair Huang, M.S. in Mechanical Engineering, Stanford University, graduated 2023.

Albert Li*, M.S. in Mechanical Engineering, Stanford University, graduated 2021.

Gabriela Bravo Illanes, M.S. in Mechanical Engineering, Stanford University, graduated 2021.

Luciana Frazao, M.S. in Mechanical Engineering, Stanford University, graduated 2021.

Ewurama Nyarkoah Karikari, M.S. in Mechanical Engineering, Stanford University, graduated 2021.

Junwu Zhang*, M.S. in Mechanical Engineering, Stanford University, graduated 2021.
Alexander Maynard, M.S. in Aeronautics & Astronautics, Stanford University, graduated 2021.
Moromoke Adekanye, M.S. in Mechanical Engineering, Stanford University, graduated 2021.
Holly Dinkel, M.S. in Aeronautics & Astronautics, Stanford University, graduated 2020.
Manuel Retana, M.S. in Aeronautics & Astronautics, Stanford University, graduated 2020.
Richie Ling, M.S. in Mechanical Engineering, Stanford University, graduated 2020.

Undergraduate Students

Undergraduate Research is performed for course credit, pay (either through an REU supplement to an NSF grant or from the ME Department SURI program), or volunteer participation. This is a list of undergraduates who have performed research in the ARMLab: Ankush Kundan (Fall 2022), Mathilda Kitzmann (Fall 2022), Ahmed Muhammad (Summer 2023), Angelina Zhang (Summer 2024), Billy Gao (Spring 2024), Ian Chen (Fall 2024), Kai Rayle (Spring 2024), Katelyn Chen (Summer 2023), Beck Jurasius (Winter 2022- Summer 2022) James Kelly (Winter 2020- Winter 2022), Bryn Hughes (Summer 2020 - Summer 2021), Rekha Ramanathan (Summer 2020 - Winter 2021), Ashley Marie Lowber (Autumn 2020 - Spring 2021), Beck Jurasius (from Winter 2022),

Research Experience for Teachers (RET)

At Stanford University: (through the program Ignited education) Suporn Chenhansa from Ohlone College (Summer 2020, 2021)

At the University of Pennsylvania: (through NSF funded RET) David Devard (science teacher at the School District of Philadelphia) (Summer 2017). Elissa Goldberg School Librarian at School District of Philadelphia (Summer 2016, 2017).

Ph.D. Thesis Defense and Reading Committees

Thesis Defenses:

2019: Margaret Koehler (Stanford, ME)

2020: Jooyeun Ham (Stanford, ME)

2021: Alex Grubele (Stanford, ME), Raunak Bhattacharyya (Stanford, AA, dissertation chair), Vincent Chiu (Stanford, ME), Benoit Landry (Stanford, AA), Boris Ivanovic (Stanford, AA, dissertation chair), Kunal Menda (Stanford, AA), Gwen Bryan (Stanford, ME), Wilson Ruotolo (Stanford, ME), Adam Wiktor (Stanford, AA, dissertation chair), Xiaobai Ma (Stanford, AA, dissertation chair), Haruki Nishimura (Stanford, AA, dissertation chair), Joe Lorenzetti (Stanford, AA, dissertation chair), David Stonestrom (Stanford, AA), Shenli Yuan (Stanford, ME), Mingyu Wang (Stanford, ME).

2022: Apoorva Sharma (Stanford AA, dissertation chair), Adam Wilford Caccavale (Stanford, AA), Brian Axelrod (Stanford, CS, dissertation chair), Eric Jordan Gonzalez (Stanford, ME), Zhangjie Cao (Stanford, CS, dissertation chair), Taylor Howell (Stanford, ME), Zhangjie Cao (Stanford, CS, dissertation chair).

2023: Simon Pierre Marie Le Cleac'h (Stanford, ME), Catie Cuan (Stanford, ME), Brian Do (Stanford, ME), Marsie Trego Peterson (Stanford, ME), **Eley Ng** (Stanford, ME), Adyasha Mohanty (Stanford, AA, dissertation chair), Michael Andres Lin (Stanford, ME), Erez Krinsky (Stanford, ME), Oriana Claudia Peltzer (Stanford, AA), Nathaniel Agharese (Stanford, ME), Kenneth Hoffmann (Stanford, ME), Molly Zhang (Stanford, AA, dissertation chair), John Talbot (Stanford, ME).

2024: John Talbot (Stanford, ME), Somrita Banerjee (Stanford, AA), Derek Cutler Knowles (Stanford, CS), Sinruta Banerjee (Stanford, AA, dissertation chair), Michael Raitor (Stanford, ME), Elliot Weiss (Stanford, ME), Yifeng Jiang (Stanford, CS, dissertation chair), Mika Uy (Stanford, CS), Annie Xie (Stanford, CS), Annahir Pena-Alcantara (Stanford MS&E, Chair), Joe Anthony Vincent (Stanford, AA), Joshua Ott (Stanford, AA), Trey Weber (Stanford, ME), Julia Di (Stanford, ME).

Reading Committees: Elliot Weiss (Stanford, ME), Adrian Piedra (Stanford, CS), Marsie Trego Peterson (Stanford, ME), Michael Andres Lin (Stanford, ME), Adam Wilford Caccavale (Stanford, AA), Wilson Ruotolo (Stanford, ME), Gwen Bryan (Stanford, ME), Nathan Spielberg (Stanford, ME), Eric Jordan Gonzalez (Stanford, ME), Benoit Landry (Stanford, Aero-Astro), John Talbot (Stanford, ME), Shenli Yuan (Stanford, ME), Alex Grubele (Stanford, ME), Adam Caccavale (Stanford, AA), Michael Andres Lin (Stanford, ME), Max Sokolich (University of Delaware, ME), Simon Pierre Marie Le Cleac'h (Stanford, ME), Catie Cuan (Stanford, ME), Zhangjie Cao (Stanford, CS), Trevor Halsted (Stanford, AA, ME co-advisor), Nathaniel Agharese (Stanford, ME), Jasmin Palmer (Stanford, ME), William Chong (Stanford, ME), Trey Weber (Stanford, ME), Julie Di (Stanford, ME), Marion Lepert (Stanford, ME), Dylan Mitchell Asmar (Stanford, AA), Chinmay Devmalaya (Stanford ME).

Instruction and Course Development

ENGR 15: Dynamics The application of Newton's Laws to solve 2-D and 3-D static and dynamic problems, particle and rigid body dynamics, free-body diagrams, and equations of motion, with application to mechanical, biomechanical, and aerospace systems. Computer numerical solution and dynamic response. *Stanford University: Autumn 2020, 2021, 2023, 2024. Approximately 50 students per year.*

ME 326: Collaborative Robotics This course focuses on how robots can be effective teammates with other robots and human partners. Concepts and tools will be reviewed to characterize task objectives, robot perception and control, teammate behavioral modeling, inter-agent communication, and team consensus. We will consider the application of these tools to robot collaborators, wearable robotics, and the latest applications in the relevant literature. This project-based graduate course implements algorithms in either Python or C++. Recommended: Introductory course in machine learning. *Stanford University: Winter 2022, 2023, 2024. Approximately 19 students per year*

ME 314: Robotic Dexterity This course covers fundamental principles of robotic dexterous manipulation, including kinematics, manipulator and gripper control, motion planning, contact modeling, and grasp stability. It explores robotic perception (vision and tactile) and advanced machine learning techniques (reinforcement learning and learning from demonstration). Students will apply these concepts in a hands-on group project using robotic manipulators for complex tasks. Homework assignments with both analytical and coding components will reinforce the concepts learned in class. Students should feel comfortable in Python and Linux (dual booting on a personal computer may be necessary for some assignments). *Stanford University: Spring 2025*

ME 334: Advanced Dynamics Modeling and analysis of dynamical systems. This class will cover reference frames and coordinate systems, kinematics and constraints, mass distribution, virtual work, D'Alembert's principle, Lagrange and Hamiltonian equations of motion. We will then consider select topics in controls including: dynamical system stability, feedback linearization, system observability and controllability, and system identification methods. Students will learn and apply these concepts through homework and projects that involve the simulation of dynamical systems. *Stanford University: Spring 2020, 2021, 2022, 2023, 2024. Approximately 18 students per year.*

Invited Presentations

1. Amazon Robotics [Research Symposium](#), October 25, 2024
2. Precognition Workshop, IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2024), June 18, 2024
3. (Keynote) AWARE-AI NSF Research Traineeship Program Winter Retreat, Rochester Institute of Technology, January 18, 2024
4. Princeton Mechanical and Aerospace Engineering (MAE) Seminar, Princeton, NJ, November 3, 2023
5. Bay Area Robotics Symposium, Stanford, CA, October 27, 2023
6. Society of Engineering Science 2023 Annual Technical Meeting, Soft Robotics Symposium, Minneapolis, MN, October 8, 2023
7. (Keynote) Amazon Science and Technology Summit, San Francisco CA, May 17, 2023
8. Berkeley Institute of Design (BiD) Seminar, Berkeley CA, April 26, 2023
9. [EI Seminar](#) at Massachusetts Institute of Technology (MIT), Boston MA, April 6, 2023
10. Robotics Seminar at Carnegie Mellon University, Pittsburgh PA, March 24, 2023
11. Robotics Seminar at West Virginia University, Morgantown WV, March 23, 2023
12. RCMAR 2023 Annual Meeting, (virtual), March 23, 2023
13. Bay Area Robotics Symposium, Berkeley, CA November 4, 2022
14. Robotics Seminar at Oregon State University, Corvallis OR, October 28, 2022
15. Institute for Experiential Robotics at Northeastern University Seminar Series, Boston, MA, October 19, 2022
16. (Guest Lecture) Harnessing AI for Breakthrough Innovation and Strategic Impact, Stanford, CA, July 19, 2022
17. ([Keynote](#)) Learning for Dynamics & Control Conference, Stanford, CA, June 24, 2022
18. Stanford Robotics Seminar, Stanford, CA, February 25, 2022
19. (Guest Lecture) SystemX/EE310, Stanford, CA, February 24, 2022
20. (Guest Lecture) Stanford Ignite, Stanford, CA, February 15, 2022
21. (Guest Lecture) Perspectives in Assistive Technology, Stanford, CA, February 10, 2022
22. CARS 2021 Annual Meeting, Stanford, CA, November 17, 2021
23. SystemX November Conference, Stanford, CA, November 11, 2021
24. Bay Area Robotics Symposium, Stanford, CA, October 29, 2021
25. University of Southern California CPS Seminar, October 6, 2021
26. ASME IDETC-CIE Special Early Career Session, August 17, 2021

27. GRASP Student Faculty Industry (SFI) Seminar Series, Philadelphia, PA, March 17, 2021
28. George Mason University Mechanical Engineering Department Seminar, Fairfax, VA, March 5, 2021
29. Human-Centered Artificial Intelligence (HAI) [Weekly Seminar](#), Stanford, CA, February 17, 2021
30. Berkeley DREAM/CPAR Seminar, Berkeley, CA, February 15, 2021
31. Human-Centered Interaction (HCI) Seminar, Stanford, CA, January 29, 2021
32. Bay Area Robotics Symposium, Stanford, CA, November 20, 2020
33. CARS 2020 Annual Meeting, Stanford, CA, November 11, 2020
34. SystemX November Conference, Stanford, CA, November 10, 2020
35. eWEAR Symposium, Stanford, CA, September 10, 2020
36. Bay Area Robotics Symposium, Berkeley, CA, November 15, 2019

Skills

- Collaborative Robotics, Robotic Autonomy, Machine Learning, Computer Vision, Motion Planning, Dynamics and Controls Analysis, Numerical Optimization.
- *Programming Languages*: Python, C++ , Matlab
- *Applications*: TensorFlow, Pytorch, ROS, OpenCV, Solid Works, Eigen, Gurobi, L^AT_EX
- *Operating Systems*: Linux/Unix system, Robot Operating System (ROS)
- *Robots*: Kinova Gen3, Panda Franka Emika Manipulator, Allegro Hand, Fetch Mobile Manipulator, LocoBot, Rethink Robotics Baxter and Sawyer, Locobot, KUKA iiwa and YouBot, Scarab Differential Drive.