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Publications

PUBLICATIONS

- **Double-prong ConvLSTM for spatiotemporal occupancy prediction in dynamic environments** *IEEE International Conference on Robotics and Automation (ICRA)*
Toyungyernsub, M., Itkina, M., Senanayake, R., Kochenderfer, M. J.
2021
- **Attention augmented ConvLSTM for environment prediction** *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*
Lange, B., Itkina, M., Kochenderfer, M. J.
2021
- **Dynamic Environment Prediction in Urban Scenes using Recurrent Representation Learning**
Itkina, M., Driggs-Campbell, K., Kochenderfer, M. J., IEEE
IEEE.2019: 2052–59