

Stanford

Maneekwan Toyungyernsub

Ph.D. Student in Mechanical Engineering, admitted Spring 2016

Publications

PUBLICATIONS

- **Double-prong ConvLSTM for spatiotemporal occupancy prediction in dynamic environments** *IEEE International Conference on Robotics and Automation (ICRA)*
Toyungyernsub, M., Itkina, M., Senanayake, R., Kochenderfer, M. J.
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