

Stanford

Savannah Cofer

- Ph.D. Student in Mechanical Engineering, admitted Autumn 2020
- Origami Robots Hourly Researcher, Program-Follmer, S.

Bio

BIO

Reconfigurable Origami Robotics, Stanford SHAPE Lab

PhD Mechanical Engineering

Stanford Knight-Hennessy Scholars

NSF GRFP Fellowship

Research & Scholarship

LAB AFFILIATIONS

- Sean Follmer, SHAPE LAB (8/31/2021)

Publications

PUBLICATIONS

- **Detecting Touch and Grasp Gestures Using a Wrist-Worn Optical and Inertial Sensing Network** *IEEE ROBOTICS AND AUTOMATION LETTERS*
Cofer, S., Chen, T. N., Yang, J., Follmer, S.
2022; 7 (4): 10842-10849