

Stanford

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Publications

PUBLICATIONS

- **Precise Relative Positioning via Tight-Coupling of GPS Carrier Phase and Multiple UWBs** *IEEE ROBOTICS AND AUTOMATION LETTERS*
Mohanty, A., Wu, A., Bhamidipati, S., Gao, G.
2022; 7 (2): 5757-5762
- **A Test Platform for UWB-Based Localization of Dynamic Multi-Agent Systems** *IEEE ROBOTICS AND AUTOMATION LETTERS*
Stier, D., Wu, A., Mohanty, A., Gao, G.
2022; 7 (2): 3773-3778