

Stanford

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Publications

PUBLICATIONS

- **Data-driven protection levels for camera and 3D map-based safe urban localization** *NAVIGATION-JOURNAL OF THE INSTITUTE OF NAVIGATION*
Gupta, S., Gao, G.
2021; 68 (3): 643-660
- **Data-Driven Protection Levels for Camera and 3D Map-based Safe Urban Localization**
Gupta, S., Gao, G. X., Inst Navigat
INST NAVIGATION.2020: 2483-2499
- **A Particle Filtering Framework for Integrity Risk of GNSS-Camera Sensor Fusion**
Mohanty, A., Gupta, S., Gao, G., Inst Navigat
INST NAVIGATION.2020: 2440-2452
- **Particle RAIM for Integrity Monitoring**
Gupta, S., Gao, G., Inst Navigat
INST NAVIGATION.2019: 811–26