

Stanford

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Ph.D. Student in Computer Science, admitted Autumn 2018

Publications

PUBLICATIONS

- **TrajectoTree: Trajectory Optimization Meets Tree Search for Planning Multi-contact Dexterous Manipulation** *2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*
Chen, C., Culbertson, P., Lepert, M., Schwager, M., Bohg, J.
IEEE.2021: 8262-8268