

Stanford

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Publications

PUBLICATIONS

- **FIG-OP: Exploring large-scale unknown environments on a fixed time budget** *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*
Peltzer, O., Bouman, A., Kim, S., Senanayake, R., Ott, J., Delecki, H., Sobue, M., Kochenderfer, M. J., Schwager, M., Burdick, J., Agha-mohammadi, A.
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