

Stanford

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Publications

PUBLICATIONS

- **Consensus-Based ADMM for Task Assignment in Multi-robot Teams**

Haksar, R. N., Shorinwa, O., Washington, P., Schwager, M., Asfour, T., Yoshida, E., Park, J., Christensen, H., Khatib, O.
SPRINGER INTERNATIONAL PUBLISHING AG.2022: 35-51

- **Reduced State Value Iteration for Multi-Drone Persistent Surveillance with Charging Constraints**

Washington, P. H., Schwager, M., IEEE
IEEE.2021: 6390-6397