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Publications

PUBLICATIONS

- **LocoFormer: Generalist Locomotion via Long-context Adaptation**
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  edited by Lim, J., Song, S., Park, H. W.
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- **Local Policies Enable Zero-shot Long-horizon Manipulation**
  Dalal, M., Liu, M., Talbott, W., Chen, C., Pathak, D., Zhang, J., Salakhutdinov, R.
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  IEEE.2025: 13875-13882

- **SoftMAC: Differentiable Soft Body Simulation with Forecast-based Contact Model and Two-way Coupling with Articulated Rigid Bodies and Clothes**
  Liu, M., Yang, G., Luo, S., Shao, L., IEEE
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