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Publications

PUBLICATIONS

- **DexSkin: High-Coverage Conformable Robotic Skin for Learning Contact-Rich Manipulation**
Wistreich, S., Shi, B., Tian, S., Clarke, S., Nath, M., Xu, C., Ban, Z., Wu, L.
edited by Lim, J., Song, S., Park, H. W.
JMLR-JOURNAL MACHINE LEARNING RESEARCH.2025: 769-793