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Publications

PUBLICATIONS

- Influencing leading and following in human-robot teams *AUTONOMOUS ROBOTS*
  
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- Learning latent actions to control assistive robots *AUTONOMOUS ROBOTS*
  
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- Learning Human Objectives from Sequences of Physical Corrections
  
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- Learning User-Preferred Mappings for Intuitive Robot Control
  
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- Influencing Leading and Following in Human-Robot Teams
  
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