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Publications

PUBLICATIONS

- Influencing leading and following in human-robot teams AUTONOMOUS ROBOTS
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  2021

- Learning latent actions to control assistive robots AUTONOMOUS ROBOTS
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- Learning Human Objectives from Sequences of Physical Corrections
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- Learning User-Preferred Mappings for Intuitive Robot Control
  Li, M., Losey, D. P., Bohg, J., Sadigh, D., IEEE
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- Influencing Leading and Following in Human-Robot Teams
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  MIT PRESS.2019