Publications

PUBLICATIONS

- Near-optimal Approximate Discrete and Continuous Submodular Function Minimization

- A Polynomial Time Algorithm for Log-Concave Maximum Likelihood via Locally Exponential Families

- Provably safe robot navigation with obstacle uncertainty
  INTERNATIONAL JOURNAL OF ROBOTICS RESEARCH
  Axelrod, B., Kaelbling, L., Lozano-Perez, T.
  2018; 37 (13-14): 1760–74

- Reducing FPGA Algorithm Area by Avoiding Redundant Computation
  2015 IEEE INTERNATIONAL CONFERENCE ON ROBOTICS AND AUTOMATION (ICRA)
  Axelrod, B., Laverne, M.
  2015: 503-508